

# ±15kV ESD 保护、限摆率、失效保护 真 RS-485 收发器

# UM3085E/UM3088E SOP8/DIP8

## 描述

UM3085E、UM3088E是具有±15kV ESD保护的高速RS-485收发器,包含一个驱动器和一个接收器。这些器件具有失效保护电路,可在接收器输入开路、短路或闲置时确保接收器输出为逻辑高电平。这意味着如果端接总线上的所有发射器都被禁用(高阻抗),接收器输出将为逻辑高电平。UM3085E具有低摆率驱动器,可充分降低EMI并减少因电缆端接不当引起的反射,从而实现高达500kbps的无误差数据传输,而部分限摆率的UM3088E的支持高达2.5Mbps的传输速率。所有器件均具有增强型ESD保护。所有发射器输出和接收器输入在人体模型下,受到±8kV的保护;在IEC61000-4-2 气隙放电下,受到±15kV的保护。

这些收发器在空载时或满载禁用驱动器时的典型电源电流消耗为400μA。所有器件都具有 1/8单位负载接收器输入阻抗,支持总线连接多达256个收发器,适用于半双工通信。

## 应用

- RS-485 收发器
- 电平转换器
- 工业控制局域网
- 适用于 EMI 敏感应用的收发器

## 特性

- RS-485 I/O 引脚提供 ESD 保护 ±8kV, 人体放电模型 ±15kV, IEC61000-4-2 空气间隙放电
- 真正的失效保护接收器,同时符合 EIA/TIA-485 标准
- 增强型摆率限制有助于实现无误差数据传输
- 2nA 低电流关断模式
- -7V 至+12V 共模输入电压范围
- 支持总线连接多达 256 个收发器
- 热美断
- 驱动过载限流保护

### 订购信息

Part Number	Operating Temperature	Marking Code	Packaging Type	Shipping Qty
UM3085EESA	-40°C to +85°C	UM3085EESA	SOP8	3000pcs/13 Inch Tape & Reel
UM3085EEPA	-40°C to +85°C	UM3085EEPA	DIP8	50pcs/Tube
UM3088EESA	-40°C to +85°C	UM3088EESA	SOP8	3000pcs/13 Inch Tape & Reel
UM3088EEPA	-40°C to +85°C	UM3088EEPA	DIP8	50pcs/Tube

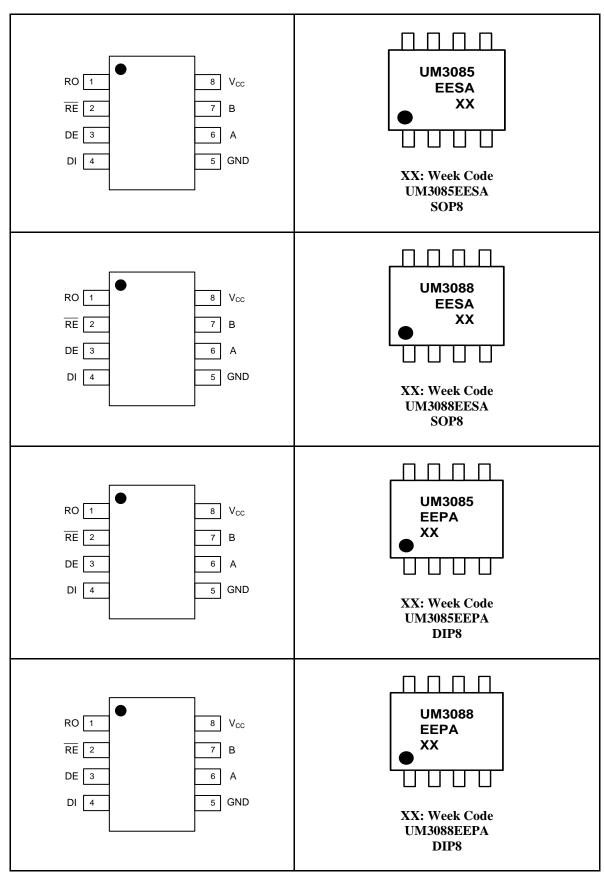
### 选型指南

Part Number	Guaranteed Date Rate (Mbps)	Low-Power Shutdown	Slew-Rate Limited	Driver/ Receiver Enable	Shutdown Current (nA)	Transceivers On Bus	±15kV ESD Protection
UM3085E	0.5	Yes	Yes	Yes	2	256	Yes
UM3088E	2.5	Yes	Yes	Yes	2	256	Yes



## **Pin Configurations**

**Top View** 



# **Pin Description**

Pin Number	Symbol	Function
1	RO	Receiver Output. If $A>B$ by -50mV, RO will be high; if $A by 200mV, RO will be low.$
2	$\overline{ ext{RE}}$	Receiver Output Enable. Drive $\overline{RE}$ low to enable Receiver, RO is high impedance when $\overline{RE}$ is high. Drive $\overline{RE}$ high and DE low to enter low-power shutdown mode.
3	DE	Driver Enable. Drive DE high to enable drivers. The outputs are high impedance when DE is low. Drive $\overline{RE}$ high and DE low to enter low-power shutdown mode.
4	DI	Driver Input. A low on DI forces output A low and output B high. Similarly, a high on DI forces output A high and output B low.
5	GND	Ground.
6	A	Non-Inverting Receiver Input and Non-Inverting Driver Output.
7	В	Inverting Receiver Input and Inverting Driver Output.
8	$V_{CC}$	Power Supply for RS-485 Transceiver.

# **Absolute Maximum Ratings**

Symbol	Parameter	Value	Unit
$V_{CC}$	Supply Voltage	+7	V
	Control Input Voltage (RE, DE)	$-0.3V$ to $(V_{CC} + 0.3V)$	V
	Driver Input Voltage (DI)	$-0.3V$ to $(V_{CC} + 0.3V)$	V
	Driver Output Voltage (A, B)	-7.5 to +12.5	V
	Receiver Input Voltage (A, B)	-7.5 to +12.5	V
	Receiver Output Voltage (RO)	$-0.3V$ to $(V_{CC} + 0.3V)$	V
$T_A$	Ambient Temperature	-40 to +85	°C
$T_{STG}$	Storage Temperature Range	-65 to +160	°C
$T_{\rm L}$	Lead Temperature for Soldering 10 seconds	+300	°C

# **DC** Electrical Characteristics

 $(V_{CC}=+5V~\pm5\%,~T_A=T_{MIN}$  to  $T_{MAX},$  unless otherwise noted. Typical values are at  $V_{CC}=+5V$  and  $T_A=+25^{\circ}C.)$  (Note 1)

Parameter	Symbol	Test	Conditions	Min	Тур	Max	Unit
SUPPLY CURRENT							
Supply Current	$ m I_{CC}$	No Load, DI=GND	$\begin{array}{c} DE=V_{CC}, \\ \overline{RE}=0V \text{ or } V_{CC} \end{array}$	0.3			mA
Suppry Current		or V <sub>CC</sub>	DE=0V, RE=0V	0.25			IIIA
Supply Current in Shutdown Mode	$I_{SHDN}$	DE=G	SND, RE=V <sub>CC</sub>	0.002		10	μΑ
LOGIC							
Input High Voltage	$V_{\mathrm{IH1}}$	DE	$\overline{E}$ , DI, $\overline{R}\overline{E}$	2.0			V
Input Low Voltage	$V_{IL1}$	DE, DI, RE				0.8	V
DI Input Hysteresis	$V_{\mathrm{HYS}}$	UM3085E			100		mV
DRIVER							
Differential Driver Output	$V_{\mathrm{OD1}}$	No L	oad, Figure 2			5	V
Differential Driver Output	$V_{\mathrm{OD2}}$	Figu	re 2, R=50Ω	1.5			V
Change-in-Magnitude of Differential Output Voltage	$\Delta V_{OD}$	_	re 2, R=50Ω (Note 2)			0.2	V
Driver Common-Mode Output Voltage	V <sub>OC</sub>	Figure 2, R=50Ω				3.0	V
Change-in-Magnitude of Common-Mode Voltage	$\Delta V_{OC}$	Figure 2, R=50Ω (Note 2)				0.2	V
Driver Short-Circuit Output	ı	V	<sub>OUT</sub> = -7V		-250		mΛ
Current (Note 3)	$I_{OSD}$	V	OUT=12V		250		mA

### **DC Electrical Characteristics (Continued)**

( $V_{CC}=+5V\pm5\%$ ,  $T_A=T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $V_{CC}=+5V$  and  $T_A=+25^{\circ}C$ .) (Note 1)

$V_{TH}$	-7V≤V					
$V_{TH}$	-7V≤V					
		-7V≤V <sub>CM</sub> ≤12V			-50	mV
$\Delta V_{TH}$	$V_{\rm CM}$	1=0V		25		mV
$R_{\rm IN}$	-7V≤V	<sub>CM</sub> ≤12V	96			kΩ
ī	DE=GND,	V <sub>IN</sub> =12V			1.0	mA
I <sub>IN2</sub>	or 5V	$V_{IN} = -7V$			-0.8	IIIA
$V_{OH}$	$I_{O}=-1.5mA, \\ V_{ID}=200mV$		V <sub>CC</sub> -1.5			V
$V_{\text{OL}}$	$I_0=2.5$ mA,	V <sub>ID</sub> =-200mV			0.4	V
$I_{OZR}$	$V_{CC}=5V, C$	)V≤V <sub>0</sub> ≤V <sub>CC</sub>			±1	μΑ
$I_{OSR}$	$0V \le V_{RO} \le V_{CC}$		±8		±60	mA
	Human Body Model			±8		
}	IEC61000-4-2 Air					kV
	R <sub>IN</sub> I <sub>IN2</sub> V <sub>OH</sub> V <sub>OL</sub> I <sub>OZR</sub>	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c c} R_{IN} & -7V \leq V_{CM} \leq 12V \\ \\ I_{IN2} & DE = GND, \\ V_{CC} = GND \\ or 5V & V_{IN} = 12V \\ \\ V_{OH} & I_O = -1.5mA, \\ V_{ID} = 200mV \\ \\ V_{OL} & I_O = 2.5mA, V_{ID} = -200mV \\ \\ I_{OZR} & V_{CC} = 5V, 0V \leq V_{O} \leq V_{CC} \\ \\ I_{OSR} & 0V \leq V_{RO} \leq V_{CC} \\ \\ \end{array}$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$

Note 1: All currents into the device are positive; all currents out of the device are negative. All voltages are referred to device ground unless otherwise noted.

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Note 2:  $\Delta V_{OD}$  and  $\Delta V_{OC}$  are the changes in  $V_{OD}$  and  $V_{OC}$ , respectively, when the DI input changes state.

Note 3: Maximum current level applies to peak current just prior to fold back current limiting; minimum current level applies during current limiting.

## **Switching Characteristics (UM3085E)**

( $V_{CC}=+5V\pm5\%$ ,  $T_A=T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $V_{CC}=+5V$  and  $T_A=+25^{\circ}C$ .)

Parameter	Symbol	<b>Test Conditions</b>	Min	Тур	Max	Unit
Maximum Data Rate	$f_{MAX}$			500		kbps
Driver Input-to-Output	$t_{DPLH}$	Figure 3 and 7, $R_{DIFF}$ =54 $\Omega$ ,	250	720	1000	***
Driver input-to-Output	$t_{DPHL}$	$C_{L1} = C_{L2} = 100 pF$	250	720	1000	ns
Driver Output Skew  t <sub>DPLH</sub> - t <sub>DPHL</sub>	t <sub>DSKEW</sub>	Figure 3 and 7, $R_{DIFF}$ =54 $\Omega$ , $C_{L1}$ = $C_{L2}$ =100pF		3	100	ns
Driver Rise or Fall Time	$t_{\mathrm{DR}},t_{\mathrm{DF}}$	Figure 3 and 7, $R_{DIFF}$ =54 $\Omega$ , $C_{L1}$ = $C_{L2}$ =100pF	200	530	750	ns
Driver Enable to Output High	$t_{\rm DZH}$	Figure 4 and 8, C <sub>L</sub> =100pF, S2 Closed			2500	ns
Driver Enable to Output Low	$t_{\mathrm{DZL}}$	Figure 4 and 8, C <sub>L</sub> =100pF, S1 Closed			2500	ns
Driver Disable Time from Low	$t_{ m DLZ}$	Figure 4 and 8, $C_L$ =15pF, S1 Closed			100	ns
Driver Disable Time from High	$t_{\mathrm{DHZ}}$	Figure 4 and 8, $C_L$ =15pF, S2 Closed			100	ns
Receiver Input to Output	$t_{ m RPLH}, \ t_{ m RPHL}$	$ V_{ID} {\ge}2.0V,$ Rise and Fall Time of $V_{ID}{\le}15ns$		127	200	ns
Differential Receiver Skew  trplh - trphl	t <sub>RSKD</sub>	Figure 6 and 9, $ V_{ID}  \ge 2.0V$ , Rise and Fall Time of $V_{ID} \le 15$ ns		3	30	ns
Receiver Enable to Output Low	$t_{RZL}$	Figure 5 and 10, C <sub>L</sub> =100pF, S1 Closed		20	50	ns
Receiver Enable to Output High	t <sub>RZH</sub>	Figure 5 and 10, C <sub>L</sub> =100pF, S2 Closed		20	50	ns
Receiver Disable Time from Low	$t_{RLZ}$	Figure 5 and 10, C <sub>L</sub> =100pF, S1 Closed		20	50	ns
Receiver Disable Time from High	$t_{RHZ}$	Figure 5 and 10, C <sub>L</sub> =100pF, S2 Closed		20	50	ns
Time to Shutdown	$t_{SHDN}$	(Note 4)	50	200	600	ns
Driver Enable from Shutdown to Output High	t <sub>DZH(SHDN)</sub>	Figure 4 and 8, C <sub>L</sub> =15pF, S2 Closed			4500	ns
Driver Enable from Shutdown to Output Low	t <sub>DZL(SHDN)</sub>	Figure 4 and 8, $C_L$ =15pF, S1 Closed			4500	ns
Receiver Enable from Shutdown to Output High	t <sub>RZH(SHDN)</sub>	Figure 5 and 10, C <sub>L</sub> =100pF, S2 Closed			3500	ns
Receiver Enable from Shutdown to Output Low	t <sub>RZL(SHDN)</sub>	Figure 5 and 10, C <sub>L</sub> =100pF, S1 Closed			3500	ns

Note 4: The device is put into shutdown by bringing  $\overline{RE}$  high and DE low. If the enable inputs are in this state for less than 50ns, the device is guaranteed not to enter shutdown. If the enable inputs are in this state for at least 600ns, the device is guaranteed to have entered shutdown.

# **Switching Characteristics (UM3088E)**

( $V_{CC}=+5V\pm5\%$ ,  $T_A=T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $V_{CC}=+5V$  and  $T_A=+25^{\circ}C$ .)

Parameter	Symbol	Test Conditions		Тур	Max	Unit
Maximum Data Rate	$f_{MAX}$			2.5		Mbps
Driver Input to Output	$t_{DPLH}$	Figure 3 and 7, $R_{DIFF}$ =54 $\Omega$ ,		34	60	***
Driver Input-to-Output	$t_{DPHL}$	$C_{L1} = C_{L2} = 100 pF$		34	60	ns
Driver Output Skew  t <sub>DPLH</sub> - t <sub>DPHL</sub>	t <sub>DSKEW</sub>	Figure 3 and 7, $R_{DIFF}$ =54 $\Omega$ , $C_{L1}$ = $C_{L2}$ =100pF		2.5	10	ns
Driver Rise or Fall Time	$t_{\mathrm{DR}},t_{\mathrm{DF}}$	Figure 3 and 7, $R_{DIFF}$ =54 $\Omega$ , $C_{L1}$ = $C_{L2}$ =100pF		14	25	ns
Driver Enable to Output High	$t_{\rm DZH}$	Figure 4 and 8, $C_L$ =100pF, S2 Closed			150	ns
Driver Enable to Output Low	$t_{ m DZL}$	Figure 4 and 8, C <sub>L</sub> =100pF, S1 Closed			150	ns
Driver Disable Time from Low	$t_{ m DLZ}$	Figure 4 and 8, $C_L$ =15pF, S1 Closed			100	ns
Driver Disable Time from High	t <sub>DHZ</sub>	Figure 4 and 8, C <sub>L</sub> =15pF, S2 Closed			100	ns
Receiver Input to Output	$t_{ m RPLH}, \ t_{ m RPHL}$	$ V_{\text{ID}} {\ge}2.0\text{V},$ Rise and Fall Time of $V_{\text{ID}}{\le}15\text{ns}$		106	150	ns
Differential Receiver Skew  t <sub>RPLH</sub> - t <sub>RPHL</sub>	t <sub>RSKD</sub>	Figure 6 and 9, $ V_{ID}  \ge 2.0V$ , Rise and Fall Time of $V_{ID} \le 15$ ns		0	10	ns
Receiver Enable to Output Low	$t_{RZL}$	Figure 5 and 10, C <sub>L</sub> =100pF, S1 Closed		20	50	ns
Receiver Enable to Output High	t <sub>RZH</sub>	Figure 5 and 10, C <sub>L</sub> =100pF, S2 Closed		20	50	ns
Receiver Disable Time from Low	$t_{RLZ}$	Figure 5 and 10, C <sub>L</sub> =100pF, S1 Closed		20	50	ns
Receiver Disable Time from High	t <sub>RHZ</sub>	Figure 5 and 10, C <sub>L</sub> =100pF, S2 Closed		20	50	ns
Time to Shutdown	t <sub>SHDN</sub>	(Note 4)	50	200	600	ns
Driver Enable from Shutdown to Output High	t <sub>DZH(SHDN)</sub>	Figure 4 and 8, C <sub>L</sub> =15pF, S2 Closed			250	ns
Driver Enable from Shutdown to Output Low	t <sub>DZL(SHDN)</sub>	Figure 4 and 8, $C_L$ =15pF, S1 Closed			250	ns
Receiver Enable from Shutdown to Output High	t <sub>RZH(SHDN)</sub>	Figure 5 and 10, C <sub>L</sub> =100pF, S2 Closed			3500	ns
Receiver Enable from Shutdown to Output Low	t <sub>RZL(SHDN)</sub>	Figure 5 and 10, C <sub>L</sub> =100pF, S1 Closed			3500	ns

Note 4: The device is put into shutdown by bringing  $\overline{RE}$  high and DE low. If the enable inputs are in this state for less than 50ns, the device is guaranteed not to enter shutdown. If the enable inputs are in this state for at least 600ns, the device is guaranteed to have entered shutdown.

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## **RS-485 Communication Function Table**

Table 1. Transmitting

	INPUTS OUTPUTS			OUTPUTS		
$\overline{RE}$	DE	DI	В	A	MODE	
X	1	1	0	1	Normal	
X	1	0	1	0	Normal	
0	0	X	High-Z	High-Z	Normal	
1	0	X	High-Z	High-Z	Shutdown	

X=Don't care; High-Z=High Impedance

Table2. Receiving

	INPUTS		OUTPUTS	MODE
$\overline{RE}$	DE	A, B	RO	MODE
0	X	> -50mV	1	Normal
0	X	< -200mV	0	Normal
0	X	Inputs Open	1	Normal
1	0	X	High-Z	Shutdown

X=Don't care; High-Z=High Impedance

# **Typical Operating Circuit**

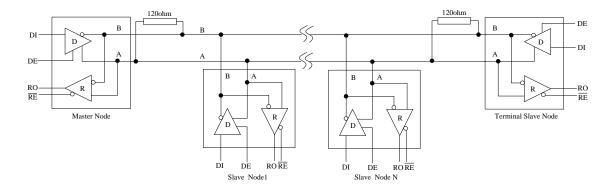


Figure 1. Typical Half-Duplex RS-485 Network

## **Test Circuit**

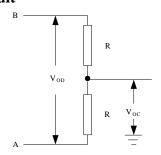


Figure 2. Driver DC Test Load

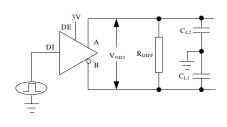
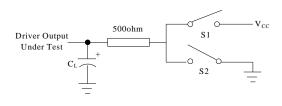


Figure 3. Driver Timing Test Circuit



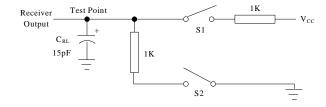


Figure 4. Driver Enable/Disable Timing Test Load

Figure 5. Receiver Enable/Disable Timing Test Load

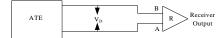


Figure 6. Receiver Propagation Delay Test Circuit

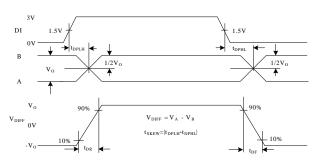


Figure 7. Driver Propagation Delays

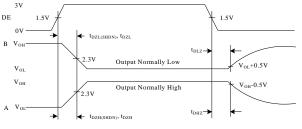


Figure 8. Driver Enable and Disable Times

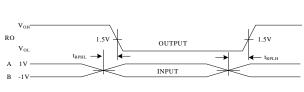


Figure 9. Receiver Propagation Delays

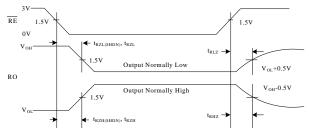


Figure 10. Receiver Enable and Disable Times



### **Detail Description**

The UM3085E, UM3088E high-speed transceivers for RS-485 communication contain one driver and one receiver. These devices feature fail-safe circuitry, which guarantees a logic-high receiver output when the receiver inputs are open or shorted, or when they are connected to a terminated transmission line with all drivers disabled. The UM3085E features reduced slew-rate driver that minimizes EMI and reduces reflections caused by improperly terminated cables, allowing error-free data transmission up to 500kbps. While partially slew-rate limited UM3088E speeds up to 2.5Mbps.

All of the parts operate from a single +5V supply. Drivers are output short-circuit current limited. Thermal shutdown circuitry protects drivers against excessive power dissipation. When activated, the thermal shutdown circuitry places the driver outputs into a high impedance state.

#### Fail-Safe

The UM3085E, UM3088E guarantees a logic-high receiver output when the receiver inputs are shorted or open, or when they are connected to a terminated transmission line with all drivers disabled. This is done by setting the receiver threshold between -50mV and -200mV. If the differential receiver input voltage (A-B) is greater than or equal to -50mV, RO is logic high. If A-B is less than or equal to -200mV, RO is logic low. In the case of a terminated bus with all transmitters disabled, the receiver's differential input voltage is pulled to 0V by the termination. With the receiver thresholds of the UM3085E, UM3088E, this results in a logic high with a 50mV minimum noise margin. Unlike previous fail-safe devices, the -50mV to -200mV threshold complies with the ±200mV EIA/TIA-485 standard.

#### ±15kV ESD Protection

As with all Union devices, ESD-protection structures are incorporated on all pins to protect against electrostatic discharges encountered during handling and assembly. The driver outputs and receiver inputs of the UM3085E, UM3088E have extra protection against static electricity. Union's engineers have developed state-of-the-art structures to protect these pins against ESD of  $\pm 15 \text{kV}$  without damage. The ESD-protected pins are tested with reference to the ground pin in a powered-down condition. They are tested to  $\pm 8 \text{kV}$  using the Human Body Model.

## **Applications Information**

#### 256 Transceivers on the Bus

The standard RS-485 receiver input impedance is  $12k\Omega$  (one unit load), and the standard driver can drive up to 32 unit loads. The Union family of transceivers have a 1/8 unit load receiver input impedance ( $96k\Omega$ ), allowing up to 256 transceivers to be connected in parallel on one communication line. Any combination of these devices and/or other RS-485 transceivers with a total of 32 unit loads or less can be connected to the line.

#### **Reduced EMI and Reflections**

The UM3085E is slew-rate limited, minimizing EMI and reducing reflections caused by improperly terminated cables. In general, a transmitter's rise time relates directly to the length of an unterminated stub, which can be driven with only minor waveform reflections. The following equation expresses this relationship conservatively:

Length= $t_{RISE} / (10 \times 1.5 \text{ ns/ft})$ 

Where  $t_{RISE}$  is the transmitter's rise time.

A system can work well with longer unterminated stubs, even with severe reflections, if the waveform settles out before the UART samples them.



#### **Low-Power Shutdown Mode**

Low-power shutdown mode is initiated by bringing both  $\overline{RE}$  high and DE low. In shutdown, the device typically draws only 2nA of supply current.  $\overline{RE}$  and DE may be driven simultaneously; the parts are guaranteed not to enter shutdown if  $\overline{RE}$  is high and DE is low for less than 50ns. If the inputs are in this state for at least 600ns, the parts are guaranteed to enter shutdown. Enable times  $t_{ZH}$  and  $t_{ZL}$  in the Switching Characteristics tables assume the part was not in a low-power shutdown state. Enable times  $t_{ZH(SHDN)}$  and  $t_{ZL(SHDN)}$  assume the parts were shut down. It takes drivers and receivers longer to become enabled from low-power shutdown mode ( $t_{ZH(SHDN)}$ ),  $t_{ZL(SHDN)}$ ) than from driver/receiver-disable mode ( $t_{ZH}$ ,  $t_{ZL}$ ).

#### **Driver Output Protection**

Two mechanisms prevent excessive output current and power dissipation caused by faults or by bus contention. The first, a foldback current limit on the output stage, provides immediate protection against short circuits over the whole common-mode voltage range. The second, a thermal shutdown circuit, forces the driver outputs into a high-impedance state if the die temperature becomes excessive.

#### Line Length vs. Data Rate

The RS-485/RS-422 standard covers line lengths up to 4000 feet. For line lengths greater than 4000 feet, repeater is required.

## **Typical Applications**

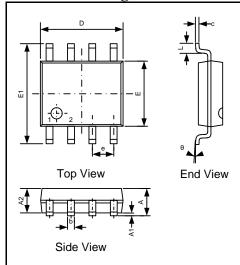
The UM3085E, UM3088E transceivers are designed for bidirectional data communications on multipoint bus transmission lines. To minimize reflections, the line should be terminated at both ends in its characteristic impedance, and stub lengths off the main line should be kept as short as possible.



# **Package Information**

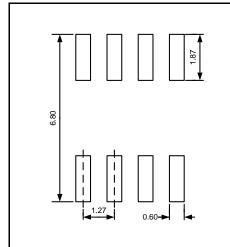
# UM3085EESA/UM3088EESA SOP8

# **Outline Drawing**



DIMENSIONS										
Crumbal	MIL	LIMET	ERS	]	INCHES	3				
Symbol	Min	Тур	Max	Min	Тур	Max				
A	1.35	1.55	1.75	0.053	0.061	0.069				
A1	0.10	-	0.25	0.004	-	0.010				
A2	1.25	-	1.65	0.049	-	0.065				
b	0.30	-	0.51	0.012	-	0.020				
c	0.15	-	0.25	0.006	-	0.010				
D	4.70	4.90	5.10	0.185	0.193	0.200				
Е	3.80	3.90	4.00	0.150	0.154	0.157				
E1	5.80	6.00	6.20	0.228	0.236	0.244				
e	1.27BSC 0.050 BSC					С				
L	0.40	-	1.27	0.016	-	0.050				
θ	0 °	-	8°	0 °	-	8°				

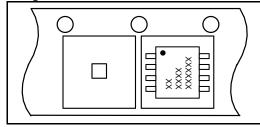
# **Land Pattern**



#### NOTES:

- 1. Compound dimension: 4.90×3.90;
- 2. Unit: mm;
- 3. General tolerance ±0.05mm unless otherwise specified;
- 4. The layout is just for reference.

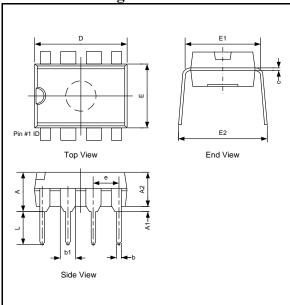
# **Tape and Reel Orientation**





# UM3085EEPA/UM3088EEPA DIP8

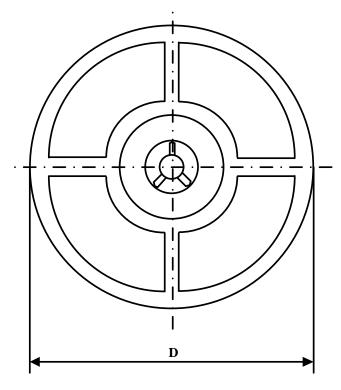
# **Outline Drawing**

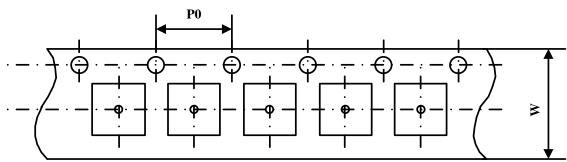


DIMENSIONS											
C11	MIL	LIME	ΓERS	INCHES							
Symbol	Min	Тур	Max	Min	Тур	Max					
A	3.71	-	4.80	0.146	-	0.189					
A1	0.38	-	-	0.015	-	-					
A2	3.20	3.40	3.60	0.126	0.134	0.142					
b	0.38	-	0.57	0.015	-	0.022					
b1	1	.52BS	С	C	0.060BS	$\Box$					
c	0.20	0.28	0.36	0.008	0.011	0.014					
D	9.00	9.20	9.50	0.354	0.362	0.374					
Е	6.20	6.40	6.60	0.244	0.252	0.260					
E1	7.32	-	7.92	0.288	-	0.312					
E2	8.40	-	9.05	0.331	-	0.356					
e	2.54TYP 0.100TYP					P					
L	3.00	3.30	3.60	0.118	0.130	0.142					



# **Packing Information**





Part Number	Package Type	Carrier Width(W)	Pitch(P0)	Reel Size(D)
UM3085EESA	SOP8	12 mm	4 mm	330 mm
UM3088EESA	SOP8	12 mm	4 mm	330 mm



## **GREEN COMPLIANCE**

Union Semiconductor is committed to environmental excellence in all aspects of its operations including meeting or exceeding regulatory requirements with respect to the use of hazardous substances. Numerous successful programs have been implemented to reduce the use of hazardous substances and/or emissions.

All Union components are compliant with the RoHS directive, which helps to support customers in their compliance with environmental directives. For more green compliance information, please visit:

http://www.union-ic.com/index.aspx?cat\_code=RoHSDeclaration

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